

## Overview

- The Engines ISA extension provides an instruction set for controlling hardware resources (either on- or off-die)
- ▶ Hardware resources can vary from implementation to implementation
- ▶ Virtualization and isolation features allow control without crossing privilege levels
- ▶ States/transitions control resource utilization profiles
- ▶ Interface allows for software-emulated engines as well

## History

- ▶ Began as an attempt to design a crypto extension
- ▶ Design evolved into generic cipher “engines”
- ▶ Eventually became generic “engine” interface
- ▶ Discussions on RISC-V `isa-dev` list suggested modifications
- ▶ Extension evolved to add direct memory access capability
- ▶ Current iteration looks increasingly like an I/O instruction set

## Hardware Additions

- ▶ *Engine Handle* register bank ( $32 \times XLEN$ )
- ▶ Arbitrary number of *engine resources* (can be per-core or shared)
- ▶ *Ownership mask* and *access mask* CSRs, each with one bit per engine resource
- ▶ Engine resource descriptions (format TBD)

## Engine Management

Instruction	Description
Function	
<b>acquire</b> <i>eh,type</i>	Acquire engine
Acquire an engine resource of type <i>type</i> , bind it to <i>eh</i>	
<b>release</b> <i>eh</i>	Release engine binding
Release the binding <i>eh</i>	
<b>ehsave</b> <i>rd,eh</i>	Save engine binding
Save the engine binding in <i>eh</i> to <i>rd</i>	
<b>ehbind</b> <i>eh,rs</i>	Load engine binding
Restore the engine handle <i>eh</i> from <i>rs</i>	

Engine management instructions allow engine resources to be acquired, released, and managed. Additionally, `ehbind` can be used to set up software-emulated engine handles, and to copy bindings to other engine handle registers.

## States and Transitions

State	Description
<code>uninit</code>	Engine is uninitialized
<code>ready</code>	Engine is initialized, but not running
<code>running</code>	Engine is actively running
<code>paused</code>	Engine is paused, but can be quickly resumed
<code>saving</code>	Engine is being saved
<code>resuming</code>	Engine is being restored

Start States	Transition	End State
<code>uninit</code>	INIT	<code>ready</code>
<code>ready, saving</code>	RESET	<code>uninit</code>
<code>ready</code>	START	<code>running</code>
<code>running</code>	STOP	<code>ready</code>
<code>any</code>	PAUSE	<code>paused</code>
<code>paused</code>	UNPAUSE	state from previous pause
<code>paused</code>	SAVEBEGIN	<code>saving</code>
<code>saving</code>	SAVEEND	<code>paused</code>
<code>uninit</code>	RESBEGIN	<code>resuming</code>
<code>resuming</code>	RESEND	<code>paused</code>

States exist to handle initialization, resource consumption, and save/restore. Transitions may perform some amount of computation as part of their function.

## Applications

- There are a number of applications for the Engines instruction set:
  - ▶ Device I/O instruction set
  - ▶ Fast direct-access hardware interface in an OS
  - ▶ Interface to on-die FPGAs
  - ▶ Application-specific accelerators (essentially on-die ASICs) for many purposes
    - ▷ Cryptography (original purpose)
    - ▷ High-precision calculations
    - ▷ Expensive computations (scientific, financial, etc)
  - ▶ Specialized coprocessor interfaces
  - ▶ Foundation for other extensions

## Future

- ▶ Revise greenfield instruction encoding, devise brownfield encoding
- ▶ Update GNU assembler/disassembler modifications
- ▶ Modify Rocket pipeline, add engine interface
- ▶ Implement sample engines (likely crypto)

## Command Instructions

Instruction	Description
<b>icmd</b> <i>eh,cmd</i>	Imperative command
<b>rcmd</b> <i>eh,cmd,rd</i>	Receive-only command
<b>s1cmd</b> <i>eh,cmd,rs1</i>	One-argument send-only command
<b>s2cmd</b> <i>eh,cmd,rs1,rs2</i>	Two-argument send-only command
<b>s3cmd</b> <i>eh,cmd,rs1,rs2,rs3</i>	Two-argument send-only command
<b>s1rcmd</b> <i>eh,cmd,rd,rs1</i>	One-argument send-receive command
<b>s2rcmd</b> <i>eh,cmd,rd,rs1,rs2</i>	Two-argument send-receive command

Command instructions issue commands to an engine bound to an engine handle. Imperative commands have no arguments; receive-only commands produce a result; send-only commands take only arguments; send-receive commands take arguments and produce a result. All command instructions can potentially produce fault traps.

## Saving and Restoring Engines

Instruction	Description
Function	
<b>savelen</b> <i>eh,rd</i>	Get state size
<b>save</b> <i>eh,rd,rs</i>	Save state word at index <i>rs</i>
<b>restore</b> <i>eh,rs1,rs2</i>	Restore word at index <i>rs2</i>
<b>savemem</b> <i>eh,addr,imm</i>	Save whole state to memory
<b>restoremem</b> <i>eh,addr,imm</i>	Restore whole state from memory

Engine states can be serialized either to registers or to memory using the save/restore instructions. Platforms may also implement secure save/restore functionality which transparently encrypts/decrypts engine states when saved and restored.

## Virtualization

Instruction	Description
Function	
<b>transm</b> <i>trans</i>	Transition multiple
Perform transition <i>trans</i> for all engines owned at all lower privilege levels	
<b>saveevt</b> <i>addr,imm</i>	Save Engine Virtualization Table
Save engine virtualization tables	
<b>loadevt</b> <i>addr,imm</i>	Load Engine Virtualization Table
Load engine virtualization tables	

The `transm` is primarily used to pause and unpauses engines when context-switching. Engine virtualization tables exist to map uniform virtual engine resources to possibly differing physical engine resources.